Symmetric ground states for doubly nonlocal equations with mass constraint

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Abstract

We prove the existence of a spherically symmetric solution for a Schrödinger equation with a nonlocal nonlinearity of Choquard type, i.e.

 $(-\Delta)^s u + \mu u = (I_\alpha * F(u))f(u) \text{ in } \mathbb{R}^N,$

where $N \geq 2$, $s \in (0, 1)$, $\alpha \in (0, N)$, $I_{\alpha}(x) = \frac{A_{N,\alpha}}{|x|^{N-\alpha}}$ is the Riesz potential, $\mu > 0$ is part of the unknowns, and $F \in C^1(\mathbb{R}, \mathbb{R})$, F' = f is assumed to be subcritical and to satisfy almost optimal assumptions. The mass of of the solution, described by its norm in the L^2 -space, is prescribed in advance by $\int_{\mathbb{R}^N} u^2 dx = c$ for some c > 0. The approach to this constrained problem relies on a Lagrange formulation and new deformation arguments. In addition, we prove that the obtained solution is also a ground state, which means that it realizes minimal energy among all the possible solutions to the problem.

Keywords: Double nonlocality, Choquard nonlinearity, Hartree term, Fractional Laplacian, Nonlinear Schrödinger equation, Normalized solutions, Symmetric solutions, Lagrange formulation, Pohozaev identity

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1 Introduction

In 1954, the nonlocal equation

$$-\Delta u + \mu u = \left(\frac{1}{4\pi|x|} * |u|^2\right) u \quad \text{in } \mathbb{R}^3$$
(1)

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was introduced by Pekar [63] in the framework of quantum mechanics, and in 1976 it arose in the work of Choquard on the modeling of an electron trapped in its own hole, in a certain approximation to the Hartree–Fock theory of one-component plasma [45] (see also [32, 29, 30]). Later, (1) was proposed by Penrose [64, 65, 66, 57] for modeling the self-gravitational collapse of a quantum mechanical wave-function (see also [69]). The first investigations of the existence and symmetry of the solutions for Equation (1) date back to [45]. Due to its physical relevance, the existence of an infinite number of standing wave solutions to (1) with prescribed L^2 -norm was faced by Lions in [49].

Variational methods were also employed to derive the existence results of standing wave solutions for the nonlinear Choquard equation without prescribed mass [55, 14, 15, 19, 43, 58, 59, 60]; the existence of L^2 -normalized solutions was also investigated when $F(t) = |t|^p$ in [72] and in [4, 18, 17] for generalized Choquard nonlinearities.

In this paper, we study the existence of solutions to the nonlocal problem

$$\begin{cases} (-\Delta)^s u + \mu u = (I_\alpha * F(u))f(u) & \text{in } \mathbb{R}^N, \\ \int_{\mathbb{R}^N} u^2 \, dx = c, \\ (\mu, u) \in (0, +\infty) \times H^s_r(\mathbb{R}^N), \end{cases}$$
(2)

where $s \in (0,1)$, $N \ge 2$, $\alpha \in (0,N)$, $F \in C^1(\mathbb{R},\mathbb{R})$ with f = F', c > 0, and μ is a Lagrange multiplier, part of the unknowns. Here, $I_{\alpha} : \mathbb{R}^N \setminus \{0\} \to \mathbb{R}$ is the Riesz potential defined by

$$I_{\alpha}(x) = A_{N,\alpha} \frac{1}{|x|^{N-\alpha}},$$

with $A_{N,\alpha} = \frac{\Gamma(\frac{N-\alpha}{2})}{2^{\alpha}\pi^{N/2}\Gamma(\frac{\alpha}{2})}$, and the symbol

$$(-\Delta)^{s}u(x) = C_{N,s} \int_{\mathbb{R}^{N}} \frac{u(x) - u(y)}{|x - y|^{N+2s}} dy$$

denotes the fractional power of the Laplace operator, where $C_{N,s} = \frac{4^s \Gamma(\frac{N+2s}{2})}{\pi^{N/2} |\Gamma(-s)|}$ and the integral is meant in the principal value sense. Finally, we indicate by

$$H^s_r(\mathbb{R}^N) = \left\{ u \in H^s(\mathbb{R}^N); \, u(x) = u(|x|) \right\}$$

the subspace composed of radially symmetric functions of the fractional Sobolev space

$$H^{s}(\mathbb{R}^{N}) = \left\{ u \in L^{2}(\mathbb{R}^{N}); \int_{\mathbb{R}^{N}} |(-\Delta)^{s/2}u|^{2} dx < \infty \right\}.$$

When $s \in (0, 1)$, the equation in (2) is a fractional PDE, as it involves derivatives and integrals of fractional order. The fractional Laplacian operator was introduced by Laskin [42] as an extension of the classical one (s = 1) in the study of NLS equations, replacing the path integral over Brownian motions with Lévy flights. This operator arises naturally in many contexts and concrete applications in various fields, such as optimization, finance, crystal dislocations, charge transport in biopolymers, flame propagation, minimal surfaces, water waves, geo-hydrology, anomalous diffusion, neural systems, phase transition and Bose-Einstein condensation (see [41, 7, 28, 22, 40, 51] and references therein). We refer to [56, 70] for a discussion of recent developments in the description of anomalous diffusion via fractional dynamics and to [3, 2] for some recent applications of fractional operators to different frameworks (analysis of the amount of bromsulphthalein in the human liver, study of thermostat systems and others). Mathematically, equations involving the fractional Laplacian, together with local nonlinearities, have been largely investigated, and some fundamental contributions can be found in [10, 9, 27]. In particular, the existence and qualitative properties of the solutions for more general classes of fractional NLS equations with local source were studied in [24, 11, 8, 36]. The mass-constrained case was, instead, recently considered in [54, 16].

In the case of Hartree type nonlinearities one of the most relevant applications arises in relativistic physics, when the nonlinearity describes the short time interactions between particles. The minimization related to the problem (2) plays a fundamental role in the mathematical description of the gravitational collapse of boson stars [48, 28]. Other applications can be found in quantum chemistry [1, 20] (see also [13] for some orbital stability results) and in the study of graphene [52].

In this work, we consider the problem (2), which presents some nonlocal characteristics in the source, as well as in the fractional diffusion.

In particular we assume

- (f1) $f \in C(\mathbb{R}, \mathbb{R});$
- (f2) there exists C > 0 such that for every $t \in \mathbb{R}$,

$$|tf(t)| \le C(|t|^{\frac{N+\alpha}{N}} + |t|^{\frac{N+\alpha+2s}{N}});$$

(f3) $F(t) = \int_0^t f(\tau) d\tau$ satisfies

$$\lim_{t \to 0} \frac{F(t)}{|t|^{\frac{N+\alpha}{N}}} = 0, \quad \lim_{t \to +\infty} \frac{F(t)}{|t|^{\frac{N+\alpha+2s}{N}}} = 0;$$

(f4) there exists $t_0 \in \mathbb{R}$, $t_0 \neq 0$ such that $F(t_0) \neq 0$.

We remark that the exponent $\frac{N+\alpha+2s}{N}$ appears as an L^2 -critical exponent for the fractional Choquard equations and the conditions (f1)–(f4) correspond to L^2 -subcritical growths.

The unconstrained case was studied by [21] for a power nonlinearity and by [6] in the case of combined local and nonlocal power-type nonlinearities; see also [68, 53, 31].

For the general class of nonlinearities of the Berestycki–Lions type [5, 59], satisfying (f1)–(f4), we introduce a Lagrangian formulation in order to obtain L^2 -normalized solutions of the nonlocal problem (2) in the spirit of [16], where it is applied for fractional NLS equations with a local source (see also [35]). Namely, set $\mathbb{R}_+ = (0, +\infty)$, a radially symmetric solution $(\mu, u) \in \mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$ of (2) corresponds to a critical point of the functional $\mathcal{T}^c : \mathbb{R}_+ \times H^s_r(\mathbb{R}^N) \to \mathbb{R}$ defined by

$$\mathcal{T}^{c}(\mu, u) = \frac{1}{2} \int_{\mathbb{R}^{N}} |(-\Delta)^{s/2} u|^{2} dx - \frac{1}{2} \int_{\mathbb{R}^{N}} (I_{\alpha} * F(u)) F(u) dx + \frac{\mu}{2} (||u||_{2}^{2} - c).$$
(3)

Using a new variant of the Palais–Smale condition [35, 37], which takes into account the Pohozaev identity, we will prove a deformation theorem which enables us to detect mini–max structures in the product space $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$, by means of a Pohozaev mountain. As stressed in [16], our deformation arguments show that solutions without Pohozaev identity are suitably deformable, and thus they do not influence the topology of the sublevels of the functional. This information could be relevant in a fractional framework since it is not known if the Pohozaev identity holds for general continuous f and general values of $s \in (0, 1)$.

We state our main results.

Theorem 1.1 Suppose $N \ge 2$, and (f1)–(f4). Then there exists $c_0 \ge 0$ such that, for any $c > c_0$, the problem (2) has a radially symmetric solution.

Theorem 1.2 Suppose $N \ge 2$, and (f1)–(f4) together with an L^2 -subcritical growth at zero, i.e.,

(f5) $\lim_{t\to 0} \frac{F(t)}{|t|^{\frac{N+\alpha+2s}{N}}} = +\infty.$

Then, for any c > 0, the problem (2) has a radially symmetric solution.

We naively notice that (f5) automatically implies (f4). We remark that, as in the local unconstrained case [39], the Mountain Pass solutions obtained in the above theorems are ground state solutions, that is, they have the least energy among all solutions; see Section 6 for details. This fact gives a strong indication of the stability properties of the found solution [25, 13].

Remark 1.3 We highlight that we assume a priori the positivity of the Lagrange multiplier μ in (2). As a matter of fact, this condition seems to be quite natural: indeed, if u is a ground state on the sphere $\int_{\mathbb{R}^N} u^2 dx = c$, and its energy is negative, then a posteriori the corresponding Lagrange multiplier μ is strictly positive (see Proposition 6.1). In addition, from a physical perspective, in the study of standing waves the multiplier μ describes the frequency of the particle, and thus it is positive; moreover, this prescribed sign is characteristic also of chemical potentials in the description of ideal gases, see [47, 67].

The paper is organized as follows. In Section 2, we introduce the functionals and the main features on the fractional setting and the nonlocal nonlinearity, while in Section 3, we introduce the Pohozaev mountain and gain some important asymptotic results on the Mountain Pass level. Then, in Section 4, a weaker version of the Palais–Smale condition, modeled on the Pohozaev identity, is obtained together with a deformation theorem. Section 5 is devoted to the proofs of Theorems 1.1 and 1.2. Finally, in Section 6, we show the equivalence of our Mountain Pass approach with the minimization approach.

2 Functional Setting

Let N > 2s. In what follows, we use the notation:

$$B(x_0, R) = \{ x \in \mathbb{R}^N; |x - x_0| < R \}, \\ \|u\|_r = \left(\int_{\mathbb{R}^N} |u|^r \, dx \right)^{1/r} \quad \text{for } r \in [1, \infty)$$

We recall the following generalized Hardy–Littlewood–Sobolev inequality [46].

Proposition 2.1 Let $\alpha \in (0, N)$, and let $r, h \in (1, +\infty)$ be such that $\frac{1}{r} - \frac{1}{h} = \frac{\alpha}{N}$. Then the map

$$L^{r}(\mathbb{R}^{N}) \to L^{h}(\mathbb{R}^{N}); f \mapsto I_{\alpha} * f$$

is continuous. In particular, if $r, t \in (1, +\infty)$ verify $\frac{1}{r} + \frac{1}{t} = \frac{N+\alpha}{N}$, then there exists a constant $C = C(N, \alpha, r, t) > 0$ such that

$$\left| \int_{\mathbb{R}^N} (I_\alpha * g) h \, dx \right| \le C \|g\|_r \|h\|_t$$

for all $g \in L^r(\mathbb{R}^N)$ and $h \in L^t(\mathbb{R}^N)$.

We endow the space $H^s(\mathbb{R}^N)$ and its subspace $H^s_r(\mathbb{R}^N)$ of radially symmetric functions with the norm

$$||u||_{H^s_r}^2 = \int_{\mathbb{R}^N} \left(|(-\Delta)^{s/2} u|^2 + u^2 \right) dx.$$

Recall the fractional Sobolev critical exponent

$$2_s^* = \frac{2N}{N-2s}.$$

In [50], Lions proved that

$$H^s_r(\mathbb{R}^N) \hookrightarrow \hookrightarrow L^q(\mathbb{R}^N)$$

whenever $N \ge 2$ and $q \in (2, 2_s^*)$. However, as shown in [12] for general $0 < s \le \frac{1}{2}$, a result in the spirit of Radial Lemma by Strauss is not available in a fractional framework.

Moreover, we recall the fractional version of the Gagliardo-Nirenberg inequality [62]

$$||u||_{r} \le C||(-\Delta)^{s/2}u||_{2}^{\beta} ||u||_{2}^{1-\beta}$$
(4)

for $u \in H^s(\mathbb{R}^N)$, $r \in [2, 2_s^*]$ and β satisfying

$$\frac{1}{r}=\frac{\beta}{2_s^*}+\frac{1-\beta}{2}.$$

In what follows, we will often denote, by q, the lower Hardy–Littlewood–Sobolev critical exponent and, by p, the L^2 -critical exponent appearing in (f2)–(f3), i.e.,

$$q = \frac{N+\alpha}{N}, \quad p = \frac{N+\alpha+2s}{N}.$$

Remark 2.2 We observe that, defining the Riesz potential by $x \mapsto \frac{A_{N,\beta}}{|x|^{\beta}}$, as some authors do, we have that the critical exponents $\frac{N+\alpha}{N} < \frac{N+\alpha+2s}{N} < \frac{N+\alpha}{N-2s}$ become respectively $\frac{2N-\beta}{N} < \frac{2N-\beta+2s}{N} < \frac{2N-\beta}{N-2s}$.

We consider the functional $\mathcal{T}^c : \mathbb{R}_+ \times H^s_r(\mathbb{R}^N) \to \mathbb{R}$ defined by

$$\mathcal{T}^{c}(\mu, u) = \frac{1}{2} \int_{\mathbb{R}^{N}} |(-\Delta)^{s/2} u|^{2} dx - \frac{1}{2} \mathcal{D}(u) + \frac{\mu}{2} (||u||_{2}^{2} - c),$$

where we set

$$\mathcal{D}(u) = \int_{\mathbb{R}^N} (I_\alpha * F(u)) F(u) \, dx$$

Using Proposition 2.1, it is easy to see that $\mathcal{T}^c \in C^1(\mathbb{R}_+ \times H^s_r(\mathbb{R}^N), \mathbb{R})$. We notice that $(\mu, u) \in \mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$ solves problem (2) if, and only if, $\partial_u \mathcal{T}^c(\mu, u) = 0$ and $\partial_\mu \mathcal{T}^c(\mu, u) = 0$.

Moreover we define the functional $\mathcal{J}: \mathbb{R}_+ \times H^s_r(\mathbb{R}^N) \to \mathbb{R}$ by setting

$$\mathcal{J}(\mu, u) = \frac{1}{2} \int_{\mathbb{R}^N} |(-\Delta)^{s/2} u|^2 \, dx - \frac{1}{2} \mathcal{D}(u) + \frac{\mu}{2} ||u||_2^2.$$
(5)

For a fixed $\mu > 0$, u is the critical point of $\mathcal{J}(\mu, \cdot)$ means that u solves

$$\begin{cases} (-\Delta)^s u + \mu u = (I_\alpha * F(u))f(u) & \text{in } \mathbb{R}^N, \\ u \in H^s_r(\mathbb{R}^N), \end{cases}$$
(6)

in the weak sense. It is immediate that

$$\mathcal{T}^{c}(\mu, u) = \mathcal{J}(\mu, u) - \frac{\mu}{2}c.$$

Observing that

$$H^s_r(\mathbb{R}^N) = \operatorname{Fix}(\operatorname{O}(N)) = \{ u \in H^s(\mathbb{R}^N) \mid \tau(Q, u) = u \text{ for each } Q \in \operatorname{O}(N) \},\$$

where O(N) is the orthogonal group of rotation matrices and the isometric action is given by

$$\tau: (Q, \mu, u) \mapsto (\mu, u(Q \cdot)); \ \mathcal{O}(N) \times (\mathbb{R}_+ \times H^s(\mathbb{R}^N)) \to \mathbb{R}_+ \times H^s(\mathbb{R}^N)$$

and observed that \mathcal{T}^c , as well as \mathcal{J} , is O(N)-invariant, we have by the Principle of Symmetric Criticality of Palais [61] (see also [71]) that every critical point of \mathcal{T}^c (resp. \mathcal{J}) restricted to $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$ is actually a critical point of \mathcal{T}^c (resp. \mathcal{J}) on the whole $\mathbb{R}_+ \times H^s(\mathbb{R}^N)$. This observation justifies our restriction onto the radial setting.

Finally, we recall that C^2 -solutions to (6) satisfy the Pohozaev identity (see [68, Proposition 2] and [21, Equation (6.1)])

$$\frac{N-2s}{2} \| (-\Delta)^{s/2} u \|_2^2 + \frac{N}{2} \mu \| u \|_2^2 = \frac{N+\alpha}{2} \mathcal{D}(u).$$
(7)

Inspired by this identity, we also introduce the Pohozaev functional $\mathcal{P} : \mathbb{R}_+ \times H^s_r(\mathbb{R}^N) \to \mathbb{R}$ by setting

$$\mathcal{P}(\mu, u) = \frac{N - 2s}{2} \| (-\Delta)^{s/2} u \|_2^2 - \frac{N + \alpha}{2} \mathcal{D}(u) + \frac{N}{2} \mu \| u \|_2^2$$
(8)

which will be used to model both the Palais–Smale condition and the geometry of the problem. We also note that

$$\mathcal{T}(\mu, u(\cdot/t)) = \frac{1}{2} t^{N-2s} \| (-\Delta)^{s/2} u \|_2^2 - \frac{1}{2} t^{N+\alpha} \mathcal{D}(u) + \frac{1}{2} \mu t^N \| u \|_2^2$$

and $\frac{d}{dt}\Big|_{t=1} \mathcal{J}(\mu, u(\cdot/t)) = \mathcal{P}(\mu, u).$

3 Asymptotic Geometry

For a fixed $\mu > 0$ we introduce the set of paths

$$\Gamma_{\mu} = \left\{ \gamma \in C([0,1], H_r^s(\mathbb{R}^N)); \, \gamma(0) = 0, \, \mathcal{J}(\mu, \gamma(1)) < 0 \right\}$$

and the Mountain Pass (MP for short) value

$$l(\mu) = \inf_{\gamma \in \Gamma_{\mu}} \max_{t \in [0,1]} \mathcal{J}(\mu, \gamma(t)).$$
(9)

Moreover we set

$$\Sigma = \left\{ (\mu, u) \in \mathbb{R}_+ \times H^s_r(\mathbb{R}^N); \, \mathcal{P}(\mu, u) > 0 \right\} \cup \left\{ (\mu, 0); \, \mu > 0 \right\},$$

and observe

$$\left\{(\mu, 0); \, \mu > 0\right\} \subset int(\Sigma),\tag{10}$$

so that the *Pohozaev mountain* is given by

$$\partial \Sigma = \left\{ (\mu, u) \in \mathbb{R}_+ \times H^s_r(\mathbb{R}^N); \, \mathcal{P}(\mu, u) = 0, \, u \neq 0 \right\}.$$

Here, the boundary of Σ is made with respect to the topology relative to the set $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$. We prove the following proposition.

Proposition 3.1 Assume (f1)–(f4). Then $\Gamma_{\mu} \neq \emptyset$ and $\partial \Sigma \neq \emptyset$. Moreover

- (i) $\mathcal{J}(\mu, u) \geq 0$ for all $(\mu, u) \in \Sigma$.
- (ii) $\mathcal{J}(\mu, u) \ge l(\mu) > 0$ for all $(\mu, u) \in \partial \Sigma$.

Proof. By exploiting (f4) and arguing as in ([59,], Proposition 2.1), we obtain the existence of a function $u \in H_r^s(\mathbb{R}^N)$ such that $\mathcal{D}(u) > 0$. Thus defined $\gamma(t) = u(\cdot/t)$ for t > 0 and $\gamma(0) = 0$ we have

- $\mathcal{J}(\mu, \gamma(t)) < 0$ for t large and $\mathcal{J}(\mu, \gamma(t)) > 0$ for t small;
- $\mathcal{P}(\mu, \gamma(t)) < 0$ for t large and $\mathcal{P}(\mu, \gamma(t)) > 0$ for t small.

The first claim ensures, after a suitable rescaling, that $\gamma \in \Gamma_{\mu}$, and, in particular, $l(\mu)$ is well defined. The second claim instead ensures, by the intermediate value theorem, that there exists a t^* , such that $\mathcal{P}(\mu, \gamma(t^*)) = 0$, and thus $(\mu, \gamma(t^*)) \in \partial \Sigma$. (i) We notice that for all $(\mu, u) \in \Sigma$

$$\mathcal{J}(\mu, u) \ge \mathcal{J}(\mu, u) - \frac{\mathcal{P}(\mu, u)}{N + \alpha} = \frac{\alpha + 2s}{2(N + \alpha)} \|(-\Delta)^{s/2}u\|_2^2 + \frac{\alpha\mu}{2(N + \alpha)} \|u\|_2^2$$

and thus (i) follows.

(ii) Let $(\mu, u) \in \partial \Sigma$, and observe that $\mathcal{D}(u) > 0$. We define again $\gamma(t) = u(\cdot/t)$ so that $t \in (0, +\infty) \mapsto \mathcal{J}(\mu, \gamma(t))$ is negative for large values of t, and it attains the maximum in t = 1. After a suitable rescaling, we have $\gamma \in \Gamma_{\mu}$ and thus

$$\mathcal{J}(\mu, u) = \max_{t \in [0,1]} \mathcal{J}(\mu, \gamma(t)) \ge l(\mu)$$
(11)

which is the claim.

To show that $l(\mu) > 0$ we argue in this way. Let $\gamma \in \Gamma_{\mu}$; by definition of Γ_{μ} and by (i) there exists t^* such that $\gamma(t^*) \in \partial \Sigma$ and $\gamma(t^*) \neq 0$, thus $\mathcal{P}(\mu, \gamma(t^*)) = 0$. This means that

$$\mathcal{J}(\mu,\gamma(t^*)) = \frac{\alpha + 2s}{2(N+\alpha)} \|(-\Delta)^{s/2}\gamma(t^*)\|_2^2 + \frac{\alpha\mu}{2(N+\alpha)} \|\gamma(t^*)\|_2^2 \simeq \|\gamma(t^*)\|_{H^s}$$

thus

$$l(\mu) \gtrsim \inf_{u \in \partial \Sigma} \|u\|_{H^s}.$$

Since, by (10), $\partial \Sigma$ is far from the line (μ , 0), we obtain that the right-hand side is strictly positive.

To see that $\mathcal{T}^{c}(\mu, u) = \mathcal{J}(\mu, u) - \frac{\mu}{2}c$ has a MP geometry in $\mathbb{R}_{+} \times H^{s}_{r}(\mathbb{R}^{N})$, it is crucial to analyze the behavior of $l(\mu)$ as $\mu \to +\infty$.

Lemma 3.2 Assume (f1)-(f4). Then,

$$\lim_{\mu \to +\infty} \frac{l(\mu)}{\mu} = +\infty.$$

Proof. We recall $p = \frac{N+\alpha+2s}{N}$ and $q = \frac{N+\alpha}{N}$. By (f3), for any $\delta > 0$, there exists $C_{\delta} > 0$ such that

$$|F(t)| \le \delta |t|^p + C_\delta |t|^q$$
 for all $t \in \mathbb{R}$.

For $v \in H^s_r(\mathbb{R}^N)$, setting $u_t = t^{N/2}v(t \cdot)$, we have

$$\mathcal{D}(u_{t}) = \mathcal{D}(t^{N/2}v(tx)) = t^{-N-\alpha}\mathcal{D}(t^{N/2}v(x))
\leq t^{-N-\alpha} \int_{\mathbb{R}^{N}} (I_{\alpha} * (\delta t^{\frac{N}{2}p}|v|^{p} + C_{\delta}t^{\frac{N}{2}q}|v|^{q})) (\delta t^{\frac{N}{2}p}|v|^{p} + C_{\delta}t^{\frac{N}{2}q}|v|^{q}) dx
= t^{2s} \int_{\mathbb{R}^{N}} (I_{\alpha} * (\delta|v|^{p} + C_{\delta}t^{-s}|v|^{q})) (\delta|v|^{p} + C_{\delta}t^{-s}|v|^{q}) dx
\equiv t^{2s} D_{\delta, C_{\delta}t^{-s}}(v).$$
(12)

Here, we write for $\delta > 0$ and $A \ge 0$,

$$D_{\delta,A}(v) = \int_{\mathbb{R}^N} (I_\alpha * (\delta |v|^p + A |v|^q)) (\delta |v|^p + A |v|^q) dx$$

$$\mathcal{J}_{\delta,A}(v) = \frac{1}{2} \| (-\Delta)^{s/2} v \|_2^2 + \frac{1}{2} \| v \|_2^2 - \frac{1}{2} D_{\delta,A}(v).$$

We also denote by $b(\delta, A)$ the MP value of $\mathcal{J}_{\delta,A}$. Taking the continuity and monotonicity property of $b(\delta, A)$ into account, with respect to each variable δ and A, and noting that $\mathcal{J}_{\delta,A}$ satisfies the Palais–Smale condition, we have

$$b(\delta, A) \to b(\delta, 0)$$
 as $A \to 0^+$,
 $b(\delta, 0) \to +\infty$ as $\delta \to 0^+$.

Thus, we have from (12) that

$$\mathcal{J}(\mu, u_t) \ge t^{2s} \left(\frac{1}{2} \| (-\Delta)^{s/2} v \|_2^2 + \frac{1}{2} \mu t^{-2s} \| v \|_2^2 - \frac{1}{2} D_{\delta, C_{\delta} t^{-s}}(v) \right).$$

Setting $t = \mu^{1/2s}$, we have

$$\mathcal{J}(\mu, u_{\mu^{1/2s}}) \ge \mu \mathcal{J}_{\delta, C_{\delta} \mu^{-1/2}}(v)$$

and thus

$$\frac{l(\mu)}{\mu} \ge b(\delta, C_{\delta}\mu^{-1/2}).$$

Therefore, we gain

$$\liminf_{\mu \to +\infty} \frac{l(\mu)}{\mu} \ge \lim_{A \to 0^+} b(\delta, A) = b(\delta, 0).$$

Since $\delta > 0$ is arbitrary, we obtain the claim for $\delta \to 0^+$.

Corollary 3.3 We have

$$B_c \equiv \inf_{(\mu,u)\in\partial\Sigma} \mathcal{T}^c(\mu,u) > -\infty.$$

Proof. By (ii) of Proposition 3.1 and Lemma 3.2, we have

$$\inf_{(\mu,u)\in\partial\Sigma} \mathcal{T}^c(\mu,u) \ge \inf_{\mu>0} \left(l(\mu) - \frac{\mu}{2}c \right) > -\infty.$$

When the nonlinearity is L^2 -subcritical in the origin, we are able to also prove the following behavior of $l(\mu)$ as $\mu \to 0^+$.

Proposition 3.4 Assume (f5) in addition to (f1)-(f4). Then,

$$\lim_{\mu \to 0^+} \frac{l(\mu)}{\mu} = 0.$$
(13)

Proof. We fix $u \in H^s_r(\mathbb{R}^N) \cap L^\infty(\mathbb{R}^N)$ with $||u||_\infty = 1$. We note that there exists $L_\sigma > 0$, such that

$$F(\sigma u(x)) \ge \sqrt{L_{\sigma}} \sigma^{p} |u(x)|^{p} \text{ for all } \sigma \in (0, 1] \text{ and } x \in \mathbb{R}^{N},$$
$$L_{\sigma} \to \infty \quad \text{as } \sigma \to 0.$$

Recalling $D_{1,0}(u) = \int_{\mathbb{R}^N} (I_\alpha * |u|^p) |u|^p \, dx$, we have for t > 0

$$\begin{aligned} \mathcal{J}(\mu, \sigma u(x/t)) &\leq \frac{1}{2} \sigma^2 t^{N-2s} \| (-\Delta)^{s/2} u \|_2^2 + \frac{\mu}{2} \sigma^2 t^N \| u \|_2^2 - \frac{1}{2} L_\sigma \sigma^{2p} t^{N+\alpha} D_{1,0}(u) \\ &= \mu^{-\frac{N-2s}{2s}} \left(\frac{1}{2} \sigma^2 \tau^{N-2s} \| \nabla u \|_2^2 + \frac{1}{2} \sigma^2 \tau^N \| u \|_2^2 - \frac{1}{2} L_\sigma \mu^{\frac{N-2s}{2s}} \mu^{-\frac{N+\alpha}{2s}} \sigma^{2p} \tau^{N+\alpha} D_{1,0}(u) \right) \\ &= \mu^{-\frac{N-2s}{2s}} \sigma^2 \left(\frac{1}{2} \| \nabla u \|_2^2 \tau^{N-2s} + \frac{1}{2} \| u \|_2^2 \tau^N - \frac{1}{2} L_\sigma \mu^{-\frac{2+\alpha}{2s}} \sigma^{2p-2} D_{1,0}(u) \tau^{N+\alpha} \right), \end{aligned}$$

where we set $t = \mu^{-\frac{1}{2s}} \tau$. Moreover setting $\sigma = \mu^{\frac{N}{4s}}$, we have

$$\mathcal{J}(\mu, \mu^{\frac{N}{4s}}u(x/(\mu^{-\frac{1}{2s}}\tau)) \le \mu\left(\frac{1}{2}\|(-\Delta)^{s/2}u\|_{2}^{2}\tau^{N-2s} + \frac{1}{2}\|u\|_{2}^{2}\tau^{N} - \frac{1}{2}L_{\mu^{N/4s}}D_{1,0}(u)\tau^{N+\alpha}\right).$$

For $\mu \in (0, 1)$, the map

$$\tau \mapsto \mu^{\frac{N}{4s}} u(x/\mu^{-\frac{1}{2s}}\tau); \ (0,+\infty) \to H^s_r(\mathbb{R}^N)$$

can be regarded as a path in Γ_{μ} . Thus

$$\frac{l(\mu)}{\mu} \le \max_{\tau \in (0,+\infty)} \left(\frac{1}{2} \| (-\Delta)^{s/2} u \|_2^2 \tau^{N-2s} + \frac{1}{2} \| u \|_2^2 \tau^N - \frac{1}{2} L_{\mu^{N/4s}} D_{1,0}(u) \tau^{N+\alpha} \right).$$

Since $L_{\mu^{N/4s}} \to +\infty$ as $\mu \to 0^+$, we have

$$R.H.S. \to 0$$
 as $\mu \to 0^+$.

Thus, we have the conclusion.

4 Palais-Smale-Pohozaev Condition

Under the assumptions (f1)–(f4), it seems hard to verify the standard Palais–Smale condition for the functional \mathcal{T}^c . As in [16], we introduce a compactness condition which is weaker than the standard Palais–Smale one (see also [35, 37, 34, 38]). Namely, we provide the following definition, recalled that $\mathbb{R}_+ \equiv (0, +\infty)$.

Definition 4.1 For $b \in \mathbb{R}$, we say that \mathcal{T}^c satisfies the Palais-Smale-Pohozaev condition at level b (in short, the (PSP)_b condition), if for any sequence $(\mu_j, u_j) \subset \mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$, such that

$$\mathcal{T}^c(\mu_j, u_j) \to b,\tag{14}$$

$$\mu_j \cdot \partial_\mu \mathcal{T}^c(\mu_j, u_j) \to 0, \tag{15}$$

$$\partial_u \mathcal{T}^c(\mu_j, u_j) \to 0 \quad strongly \ in \ (H^s_r(\mathbb{R}^N))^*,$$
(16)

$$\mathcal{P}(\mu_i, u_i) \to 0, \tag{17}$$

it happens that (μ_j, u_j) has a strongly convergent subsequence in $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$.

Remark 4.2 The $(PSP)_b$ condition introduced in Definition 4.1 looks slightly different from the one in [16]. We emphasize that $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$ with the standard metric induced by $\mathbb{R} \times H^s_r(\mathbb{R}^N)$ is not complete, and is not suitable for the deformation argument. Since $(\mathbb{R}_+, \frac{1}{x^2}dx^2)$ is complete, it is natural to introduce a related metric on $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$, that is, we regard $M = \mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$ as a Riemannian manifold with the metric

$$((\nu_1, w_1), (\nu_2, w_2))_{T_{(\mu, u)}M} = \frac{1}{\mu^2} \nu_1 \nu_2 + (w_1, w_2)_{H^s_r}$$

for (ν_1, w_1) , $(\nu_2, w_2) \in T_{(\mu, u)}M$, $(\mu, u) \in M$. It is easy to see that $(M, (\cdot, \cdot)_{TM})$ is a complete Riemannian manifold. We regard \mathcal{T}^c as a functional defined on M. We have

$$\|(\partial_{\mu}\mathcal{T}^{c}(\mu, u), \partial_{u}\mathcal{T}^{c}(\mu, u))\|^{2}_{(T_{(\mu, u)}M)^{*}} = \mu^{2}|\partial_{\mu}\mathcal{T}^{c}(\mu, u)|^{2} + \|\partial_{u}\mathcal{T}^{c}(\mu, u)\|^{2}_{(H^{s}_{r})^{*}}.$$

Thus (15)-(16) are equivalent to

$$\|(\partial_{\mu}\mathcal{T}^{c}(\mu, u), \partial_{u}\mathcal{T}^{c}(\mu, u))\|_{(T_{(\mu, u)}M)^{*}} \to 0.$$
(18)

Moreover, setting

$$\widetilde{\mathcal{T}}^c(\lambda, u) = \mathcal{T}^c(e^{\lambda}, u) : \mathbb{R} \times H^s_r(\mathbb{R}^N) \to \mathbb{R},$$

we can observe that $(\lambda_j, u_j) \subset \mathbb{R} \times H^s_r(\mathbb{R}^N)$ satisfies

$$\begin{aligned} \partial_{\lambda} \widetilde{\mathcal{T}}^{c}(\lambda_{j}, u_{j}) &\to 0, \\ \|\partial_{u} \widetilde{\mathcal{T}}^{c}(\lambda_{j}, u_{j})\|_{(H^{s}_{r})^{*}} &\to 0 \end{aligned}$$

if and only if $(\mu_j, u_j) = (e^{\lambda_j}, u_j)$ satisfies (18).

We remark that this compactness condition takes the scaling properties of \mathcal{T}^c into consideration through the Pohozaev functional \mathcal{P} . We now show the following crucial result.

Theorem 4.3 Assume (f1)–(f3). Let b < 0. Then, \mathcal{T}^c satisfies the $(PSP)_b$ condition on $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$.

Proof. Let b < 0 and $(\mu_j, u_j) \subset \mathbb{R} \times H^s_r(\mathbb{R}^N)$ be a sequence satisfying (14)–(17). First we note that, by (15), we have

$$\mu_j \left(\|u_j\|_2^2 - c \right) \to 0. \tag{19}$$

 $Step \ 1: \ \liminf_{j \to \infty} \mu_j > 0 \ \text{and} \ \|u_j\|_2^2 \to c.$

By (17) and (14), we have

$$o(1) = \mathcal{P}(\mu_j, u_j) = \frac{N - 2s}{2} \| (-\Delta)^{s/2} u_j \|_2^2 + (N + \alpha) \Big(\mathcal{T}^c(\mu_j, u_j) - \frac{1}{2} \| (-\Delta)^{s/2} u_j \|_2^2 - \frac{\mu_j}{2} \big(\| u_j \|_2^2 - c \big) \Big) + \frac{N}{2} \mu_j \| u_j \|_2^2$$

$$= -\frac{\alpha + 2s}{2} \| (-\Delta)^{s/2} u_j \|_2^2 + (N + \alpha) (b + o(1)) + \frac{N}{2} \mu_j c + o(1),$$

Here, we have used (19). Since b < 0, we have $\liminf_{j\to\infty} \mu_j > 0$. Thus (19) implies $||u_j||_2^2 \to c$.

Step 2: $\|(-\Delta)^{s/2}u_j\|_2^2$ and μ_j are bounded.

Since $\varepsilon_j \equiv \|\partial_u \mathcal{T}^c(\mu_j, u_j)\|_{(H^s_r(\mathbb{R}^N))^*} \to 0$, we have

$$\|(-\Delta)^{s/2}u_j\|_2^2 - \int_{\mathbb{R}^N} (I_\alpha * F(u_j))f(u_j)u_j \, dx + \mu_j \|u_j\|_2^2 \le \varepsilon_j \|u_j\|_{H^s_r}.$$
 (20)

Note that $\frac{2Np}{N+\alpha} \in (2, 2_s^*)$. Moreover, we observe that, by (f3), for $\delta > 0$ fixed, there exists $C_{\delta} > 0$ such that

$$|F(t)| \le \delta |t|^p + C_\delta |t|^{\frac{N+\alpha}{N}}, \quad t \in \mathbb{R},$$

where $p = \frac{N + \alpha + 2s}{N}$, and thus

$$\|F(u_j)\|_{\frac{2N}{N+\alpha}} \le \delta \||u_j|^p\|_{\frac{2N}{N+\alpha}} + C_{\delta} \||u_j|^{\frac{N+\alpha}{N}}\|_{\frac{2N}{N+\alpha}} = \delta \|u_j\|_{\frac{2Np}{N+\alpha}}^p + C_{\delta} \|u_j\|_{2}^{\frac{N+\alpha}{N}}$$

Therefore, by (f2) we have

$$\begin{split} &\int_{\mathbb{R}^{N}} (I_{\alpha} * |F(u_{j})|) |f(u_{j})u_{j}| \, dx \\ &\leq C \|F(u_{j})\|_{\frac{2N}{N+\alpha}} \|f(u_{j})u_{j}\|_{\frac{2N}{N+\alpha}} \\ &\leq C \left(\delta \|u_{j}\|_{\frac{2Np}{N+\alpha}}^{p} + C_{\delta} \|u_{j}\|_{2}^{\frac{N+\alpha}{N}} \right) \cdot C' \left(\|u_{j}\|_{\frac{2Np}{N+\alpha}}^{p} + \|u_{j}\|_{2}^{\frac{N+\alpha}{N}} \right) \\ &= CC' \delta \|u_{j}\|_{\frac{2Np}{N+\alpha}}^{2p} + CC'(\delta + C_{\delta}) \|u_{j}\|_{\frac{2Np}{N+\alpha}}^{p} \|u_{j}\|_{2}^{\frac{N+\alpha}{N}} + CC'C_{\delta} \|u_{j}\|_{2}^{\frac{2(N+\alpha)}{N}} \\ &= CC' \delta \|u_{j}\|_{\frac{2Np}{N+\alpha}}^{2p} + CC'(\delta + C_{\delta}) \left(\frac{\delta}{2} \|u_{j}\|_{\frac{2Np}{N+\alpha}}^{2p} + \frac{1}{2\delta} \|u_{j}\|_{2}^{\frac{2(N+\alpha)}{N}} \right) + CC'C_{\delta} \|u_{j}\|_{2}^{\frac{2(N+\alpha)}{N}} \\ &\leq C'' \delta \|u_{j}\|_{\frac{2Np}{N+\alpha}}^{2p} + C_{\delta}'' \|u_{j}\|_{2}^{\frac{2(N+\alpha)}{N}} \end{split}$$

and thus, by Gagliardo–Nirenberg inequality (4), with $r = \frac{2Np}{N+\alpha}$ and $\beta = \frac{1}{p}$, we derive

$$\begin{aligned} \|(-\Delta)^{s/2} u_j\|_2^2 + \mu_j \|u_j\|_2^2 &\leq \int_{\mathbb{R}^N} (I_\alpha * |F(u_j)|) |f(u_j) u_j| \, dx + \varepsilon_j \|u_j\|_{H^s_r} \\ &\leq C'' \delta \|(-\Delta)^{s/2} u_j\|_2^2 \|u_j\|_2^{2(p-1)} + C''_\delta \|u_j\|_2^{\frac{2(N+\alpha)}{N}} + \varepsilon_j \|u_j\|_{H^s_r}. \end{aligned}$$

Since $||u_j||_2^2 = c + o(1)$, we have

$$(1 - C'' \delta(c + o(1))^{p-1}) \| (-\Delta)^{s/2} u_j \|_2^2 + \mu_j (c + o(1))$$

$$\leq C''_{\delta} (c + o(1))^{\frac{N+\alpha}{N}} + \varepsilon_j (\| (-\Delta)^{s/2} u_j \|_2^2 + c + o(1))^{1/2}.$$

For a small enough δ , we have a boundedness of $\|(-\Delta)^{s/2}u_j\|_2$ and μ_j .

Step 3: Convergence in $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$.

By Steps 1–2, the sequence (μ_j, u_j) is bounded in $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$ and thus, after extracting a subsequence denoted in the same way, we may assume that $\mu_j \to \mu_0 > 0$ and $u_j \to u_0$ weakly in $H^s_r(\mathbb{R}^N)$ for some $(\mu_0, u_0) \in \mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$.

Step 4: Conclusion.

Taking into account the assumptions (f1)-(f4), we obtain

$$\int_{\mathbb{R}^N} (I_\alpha * F(u_j)) f(u_j) u_0 \, dx \to \int_{\mathbb{R}^N} (I_\alpha * F(u_0)) f(u_0) u_0 \, dx$$

and

$$\int_{\mathbb{R}^N} (I_\alpha * F(u_j)) f(u_j) u_j \, dx \to \int_{\mathbb{R}^N} (I_\alpha * F(u_0)) f(u_0) u_0 \, dx.$$

Thus, we derive that $\langle \partial_u \mathcal{T}^c(\mu_j, u_j), u_j \rangle \to 0$ and $\langle \partial_u \mathcal{T}^c(\mu_j, u_j), u_0 \rangle \to 0$, and hence

$$\|(-\Delta)^{s/2}u_j\|_2^2 + \mu_0 \|u_j\|_2^2 \to \|(-\Delta)^{s/2}u_0\|_2^2 + \mu_0 \|u_0\|_2^2$$

which implies a $u_j \to u_0$ strongly in $H^s_r(\mathbb{R}^N)$.

Remark 4.4 We emphasize that the $(PSP)_b$ condition does not hold at level b = 0; it is sufficient to consider an infinitesimal sequence $(\mu_j, 0)$ with $\mu_j \to 0$.

Now, we introduce the set of critical points of \mathcal{T}^c satisfying the Pohozaev identity, that is

$$K_b = \left\{ (\mu, u) \in \mathbb{R}_+ \times H^s_r(\mathbb{R}^N) \mid \mathcal{T}^c(\mu, u) = b, \, \partial_\mu \mathcal{T}^c(\mu, u) = 0, \, \partial_u \mathcal{T}^c(\mu, u) = 0, \, \mathcal{P}(\mu, u) = 0 \right\}.$$

Notice that in the definition of K_b the condition $\mathcal{P}(\mu, u) = 0$ is not trivial, since it is not known if the equality is satisfied by every solution, for general continuous f and $s \in (0, 1)$ (see [21, 68] and Proposition 6.1 for some particular cases). In fact, we can not generally recognize that the standard set of critical points at level b is compact, and thus we restrict this to the set K_b of critical points satisfying the Pohozaev identity.

Moreover, for each $b \in \mathbb{R}$, we introduce the following notation for sublevels

$$[\mathcal{T}^c \le b] = \left\{ (\mu, u) \in \mathbb{R}_+ \times H^s_r(\mathbb{R}^N) \mid \mathcal{T}^c(\mu, u) \le b \right\}.$$

Following arguments in ([37,], Proposition 4.5) (see also [35,], Proposition 3.1 and Corollary 4.3), we can establish the following deformation theorem for the functional \mathcal{T}^c .

Theorem 4.5 Assume (f1)–(f3) and b < 0. Then, K_b is compact in $\mathbb{R}_+ \times H^s_r(\mathbb{R}^N)$ and $K_b \cap (\mathbb{R}_+ \times \{0\}) = \emptyset$. Moreover, for any open neighborhood U of K_b and $\bar{\varepsilon} > 0$, there exists an $\varepsilon \in (0, \bar{\varepsilon})$ and a continuous map

$$\eta(t,\mu,u):[0,1]\times\mathbb{R}_+\times H^s_r(\mathbb{R}^N)\to\mathbb{R}_+\times H^s_r(\mathbb{R}^N)$$

such that

 $(1^{o}) \quad \eta(0,\mu,u) = (\mu,u) \quad \forall (\mu,u) \in \mathbb{R}_{+} \times H^{s}_{r}(\mathbb{R}^{N});$ $(2^{o}) \quad \eta(t,\mu,u) = (\mu,u) \quad \forall (t,\mu,u) \in [0,1] \times [\mathcal{T}^{c} \leq b - \bar{\varepsilon}];$ $(3^{o}) \quad \mathcal{T}^{c}(\eta(t,\mu,u)) \leq \mathcal{T}^{c}(\mu,u) \quad \forall (t,\mu,u) \in [0,1] \times \mathbb{R}_{+} \times H^{s}_{r}(\mathbb{R}^{N});$ $(4^{o}) \quad \eta(1, [\mathcal{T}^{c} \leq b + \varepsilon] \setminus U) \subset [\mathcal{T}^{c} \leq b - \varepsilon];$ $(5^{o}) \quad \eta(1, [\mathcal{T}^{c} \leq b + \varepsilon]) \subset [\mathcal{T}^{c} \leq b - \varepsilon] \cup U;$ $(6^{o}) \quad if \ K_{b} = \emptyset, \ we \ have \ \eta(1, [\mathcal{T}^{c} \leq b + \varepsilon]) \subset [\mathcal{T}^{c} \leq b - \varepsilon].$

5 Minimax Theorem

For any c > 0, let B_c be the constant defined in Corollary 3.3. As a minimax class for \mathcal{T}^c , we define

$$\Lambda_c = \{ \xi \in C([0,1], \mathbb{R}_+ \times H^s_r(\mathbb{R}^N)); \xi(0) \in \mathbb{R}_+ \times \{0\}, \\ \mathcal{T}^c(\xi(0)) \le B_c - 1, \ \xi(1) \notin \Sigma \text{ and } \mathcal{T}^c(\xi(1)) \le B_c - 1 \}.$$

In the following Proposition 5.1 we prove that $\Lambda_c \neq \emptyset$; moreover, by (10) we have $\xi([0,1]) \cap \partial \Sigma \neq \emptyset$ for each $\xi \in \Lambda_c$. Therefore from Corollary 3.3, the mini-max value

$$\beta_c = \inf_{\xi \in \Lambda_c} \max_{t \in [0,1]} \mathcal{T}^c(\xi(t))$$
(21)

is well-defined and finite. Since the Palais–Smale–Pohozaev condition holds for $b \in (-\infty, 0)$, it is important to estimate β_c . We have the following proposition.

Proposition 5.1 Assume (f1)–(f4). For each c > 0 we have $\Lambda_c \neq \emptyset$ and

$$\beta_c \le l(\mu) - \frac{\mu}{2}c, \quad for \ any \ \mu > 0.$$
(22)

As a consequence

(i) for a sufficiently large c, that is

$$c > c_0 = 2 \inf_{\mu > 0} \frac{l(\mu)}{\mu}$$

we have $\beta_c < 0$;

- (ii) if (f5) holds, then $\beta_c < 0$ for all c > 0;
- (*iii*) $\lim_{c \to +\infty} \frac{\beta_c}{c} = -\infty.$

Proof. (i) Let $\mu > 0$ and $\gamma \in \Gamma_{\mu} \neq \emptyset$. By definition we have $\mathcal{D}(\gamma(1)) > 0$, thus $\mathcal{J}(\mu, \gamma(1)(\cdot/t)) \rightarrow -\infty$ and $\mathcal{P}(\mu, \gamma(1)(\cdot/t)) \rightarrow -\infty$ as $t \rightarrow +\infty$. Thus for $L \gg 0$

$$\mathcal{T}^c(\mu, \gamma(1)(\cdot/L)) \le B_c - 1, \quad \gamma(1)(\cdot/L) \notin \Omega.$$

We also note that $\mathcal{T}^c(t,0) \to -\infty$ as $t \to +\infty$. Therefore, joining the path γ_{μ} with the map $t \mapsto (\mu + Lt, 0)$ with a large enough $L \gg 0$, we can find a path $\xi \in \Lambda_c$ such that

$$\max_{t\in[0,1]} \mathcal{T}^c(\xi(t)) \le \max_{t\in[0,1]} \mathcal{J}(\mu,\gamma(t)) - \frac{\mu}{2}c,$$

and thus (22). For, $c \gg 0$ we have the claim:

(ii) If (f5) holds, we can apply Proposition 3.4 to obtain

$$\lim_{\mu \to 0} \frac{l(\mu) - \frac{c}{2}\mu}{\mu} = -\frac{c}{2} < 0, \tag{23}$$

and, thus, the claim by (22).

(iii) Finally for any $\mu > 0$ we have, by (22),

$$\limsup_{c \to +\infty} \frac{\beta_c}{c} \le \lim_{c \to +\infty} \left(\frac{l(\mu)}{c} - \frac{\mu}{2} \right) = -\frac{\mu}{2}.$$

Since μ is arbitrary, we have (iii).

Proof of Theorem 1.1 and Theorem 1.2. Using Theorem 4.5, we derive that the level $\beta_c < 0$, defined in (21), is critical, and thus Theorem 1.1 and Theorem 1.2 hold.

6 L^2 -Ground States

We introduce the functional $\mathcal{L}: S_c \to \mathbb{R}$ defined by

$$\mathcal{L}(u) = \frac{1}{2} \int_{\mathbb{R}^N} |(-\Delta)^{s/2} u|^2 \, dx - \frac{1}{2} \int_{\mathbb{R}^N} (I_\alpha * F(u)) F(u) \, dx \tag{24}$$

on the sphere

$$S_c = \left\{ u \in H^s_r(\mathbb{R}^N); \, \|u\|_2^2 = c \right\}.$$

We consider the ground state level

$$\kappa_c = \inf_{u \in S_c} \mathcal{L}(u).$$

We pass this to recognize that the Mountain Pass solution found in Theorems 1.1 and 1.2 is a ground state solution, namely, a minimizer of \mathcal{L} on the sphere.

Proposition 6.1 Assume (f1)–(f4), and let $c \ge c_0$, where c_0 is introduced in Proposition 5.1. If (f5) holds, then take $c_0 = 0$. We have that the following statements hold.

(i) Every Mountain Pass solution at level β_c is a Pohozaev minimum on the product space, that is

$$\beta_c = B_c$$

where B_c is defined in Corollary 3.3.

(ii) The Mountain Pass level and the ground state level coincide, i.e.,

$$\kappa_c = \beta_c. \tag{25}$$

In particular, thanks to Theorem 1.1, there exists a ground state of $\mathcal{L}_{|S_c}$.

- (iii) Every ground state of $\mathcal{L}_{|S_c}$ is a solution of problem (2), i.e., the associated Lagrange multiplier is positive.
- (iv) Every ground state of $\mathcal{L}_{|S_c}$ satisfies the Pohozaev identity (7) with μ the associated (positive) Lagrange multiplier. Thanks to (25), the same conclusion holds for every Mountain Pass solution at level β_c .

Proof. (i) From (22) and (ii) of Proposition 3.1 we have

$$\beta_c \le \inf_{\mu>0} \left(l(\mu) - \frac{\mu}{2}c \right) \le B_c$$

On the other hand, each path of Λ_c passes through $\partial \Sigma$ by definition, and thus

$$\beta_c \ge B_c$$

which gives the claim (i).

(ii) Let u_* be the Mountain Pass solution obtained in Theorems 1.1 and 1.2, which verifies $||u_*||_2^2 = c$. Thus,

$$\kappa_c \le \mathcal{L}(u_*) = \beta_c < 0. \tag{26}$$

In particular, by (26) we can find a minimizing sequence $(u_n)_n \subset S_c$ for κ_c satisfying $\mathcal{L}(u_n) < 0$, and thus we can set

$$\mu_n = \frac{2}{Nc} \left(\frac{\alpha + 2s}{2} \| (-\Delta)^{s/2} u_n \|_2^2 - (N + \alpha) \mathcal{L}(u_n) \right) > 0$$

so that $\mathcal{P}(\mu_n, u_n) = 0$, i.e., $(\mu_n, u_n) \in \partial \Sigma$. At this point Corollary 3.3 and (i) imply

$$\kappa_c + o(1) = \mathcal{L}(u_n) = \mathcal{T}^c(\mu_n, u_n) \ge B_c = \beta_c.$$

Passing to the limit, together with (26), we have (25).

(iii)–(iv) Let u_0 be a minimizer of \mathcal{L} on S_c . Corresponding to u_0 , there exists a Lagrange multiplier $\mu_0 \in \mathbb{R}$ such that

$$(-\Delta)^{s/2}u_0 + \mu_0 u_0 = (I_\alpha * F(u_0))f(u_0),$$

and thus, in particular,

$$\|(-\Delta)^{s/2}u_0\|_2^2 + \mu_0 \|u_0\|_2^2 = \int_{\mathbb{R}^N} (I_\alpha * F(u_0))f(u_0)u_0 \, dx.$$
(27)

We show first that u_0 satisfies the Pohozaev identity. In fact, we consider the \mathbb{R} -action $\Phi : \mathbb{R} \times S_c \to S_c$ defined by

$$(\Phi_{\theta}v)(x) = e^{\frac{N}{2}\theta}v(e^{\theta}x), \qquad (28)$$

since $\|\Phi_{\theta}v\|_2^2 = \|v\|_2^2$. Then we have

$$\mathcal{L}(\Phi_{\theta}u_0) = \frac{1}{2}e^{2s\theta} \|(-\Delta)^{s/2}u_0\|_2^2 - \frac{1}{2}e^{-(N+\alpha)\theta} \int_{\mathbb{R}^N} (I_{\alpha} * F(e^{\frac{N}{2}\theta}u_0))F(e^{\frac{N}{2}\theta}u_0) \, dx.$$

Since u_0 is a minimizer, we have $\frac{d}{d\theta}\Big|_{\theta=0}\mathcal{L}(\Phi_{\theta}u_0)=0$, that is,

$$s\|(-\Delta)^{s/2}u_0\|_2^2 + \frac{N+\alpha}{2}\int_{\mathbb{R}^N} (I_\alpha * F(u_0))F(u_0)\,dx - \frac{N}{2}\int_{\mathbb{R}^N} (I_\alpha * F(u_0))f(u_0)u_0\,dx = 0.$$
 (29)

From (27) and (29), the Pohozaev identity follows

$$\frac{N-2s}{2} \|(-\Delta)^{s/2} u_0\|_2^2 + \frac{N}{2} \mu_0 \|u_0\|_2^2 = \frac{N+\alpha}{2} \mathcal{D}(u_0).$$
(30)

Finally, from (26) we have $\mathcal{L}(u_0) = \kappa_c < 0$, that is

$$\frac{1}{2} \| (-\Delta)^{s/2} u_0 \|_2^2 - \frac{1}{2} \mathcal{D}(u_0) = \kappa_c < 0, \tag{31}$$

which joined to (30) gives $\mu_0 > 0$. This concludes the proof.

Remark 6.2 We notice that, by using only

$$0 > \beta_c \ge \kappa_c \ge B_c > -\infty$$

and the $(PSP)_{\kappa_c}$ condition, we can directly obtain the existence of a minimizer \tilde{u} of \mathcal{L} on S_c . We provide only an outline of the proof, and refer to [16] for details. Indeed, consider again the action Φ_{θ} on S_c defined in (28). Set

$$\widehat{\mathcal{L}}(\theta, u) = \mathcal{L}(\Phi_{\theta} u) : \mathbb{R} \times S_c \to \mathbb{R},$$

we observe

$$\kappa_c = \inf_{(\theta, u) \in \mathbb{R} \times S_c} \widehat{\mathcal{L}}(\theta, u).$$

Since $\kappa_c \in \mathbb{R}$, applying Ekeland Principle to $\widehat{\mathcal{L}} : \mathbb{R} \times S_c \to \mathbb{R}$, we find a sequence $(\theta_j, u_j) \subset \mathbb{R} \times S_c$ such that

$$\widehat{\mathcal{L}}(\theta_j, u_j) \to \kappa_c, \ \partial_{\theta} \widehat{\mathcal{L}}(\theta_j, u_j) \to 0, \ \partial_u \widehat{\mathcal{L}}(\theta_j, u_j) \to 0.$$

Setting $\hat{u}_j = \Phi_{\theta_j} u_j$, we observe that, for a suitable $\mu_j > 0$, (μ_j, \hat{u}_j) is a $(PSP)_{\kappa_c}$ -sequence for \mathcal{T}^c .

Thus, provided that $\kappa_c < 0$, thanks to Theorem 4.3, \hat{u}_j converges up to a subsequence, to a minimizer of \mathcal{L} on S_c , and, therefore, the claim.

7 Conclusions

In this paper, we prove the existence of a radially symmetric solution to the nonlocal problem

$$(-\Delta)^s u + \mu u = (I_\alpha * F(u))f(u) \text{ in } \mathbb{R}^N$$

coupled with the mass constraint $\int_{\mathbb{R}^N} u^2 dx = c$. The result is obtained for general values of $s \in (0,1)$ and $\alpha \in (0,N)$, and by assuming quite general assumptions on the function f, which are almost optimal and include some particular cases such as pure powers $f(t) \sim t^r$, cooperating powers $f(t) \sim t^r + t^h$, competing powers $f(t) \sim t^r - t^h$ and saturable functions $f(t) \sim \frac{t^3}{1+t^2}$ (which arise, for instance, in nonlinear optics [23]).

The existence is obtained through a Lagrange formulation of the constrained problem, performing a minimax argument on a product space by means of a Pohozaev mountain. The use of the Pohozaev identity in the definition of the Palais–Smale condition allows to overcome the problem of the lack of a Pohozaev identity for general solutions, typical of the fractional framework.

Finally, we show that the Mountain Pass solution assumes the minimal energy among all the possible solutions with the same mass, which points out the physical relevance of the found solution.

When $s = \frac{1}{2}$, N = 3, $\alpha = 2$ and $f(t) = |t|^{r-2}t$, we obtain

$$\sqrt{-\Delta}u + \mu u = \left(\frac{1}{|x|} * |u|^r\right) |u|^{r-2}u \quad \text{in } \mathbb{R}^3.$$

In the L^2 -critical case r = 2, the equation is the well-known massless boson stars equation [26, 44, 33]; in this case, the quantity $\int_{\mathbb{R}^3} u^2 dx = c$ represents the total L^2 -mass of the body and plays a fundamental role in the study of the gravitational collapse of boson stars, where a critical value is given by the Chandrasekhar limiting mass. In this paper, we address the subcritical case $r \in (\frac{5}{3}, 2)$, but we believe that this result, together with the developed minimax tools, can be

a first step towards the study of the L^2 -mass critical case, since, in this case, the minimization approch is not well posed. Moreover, the high generality assumed on the function f could be useful in the study of different physical problems.

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